

# Neural network parsing

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# Recap

$c \leftarrow c_0(S)$

**while**  $\neg isFinal(c)$  **do**

$t \leftarrow g(c)$

$c \leftarrow t(c)$

**end while**

- $c$ : parser state
- $c_0$ : initial parser state
- $t$ : transition
- $g$ : parsing guide

- Next question: what function do we use as  $g$ ?
- Answer: a probabilistic model:  $p(t|c)$
- Benefits:
  - Well-understood methods for optimization.
  - Provides a good basis for beam search.

# Data-driven models

# Introduction

- Goal of of a guide during parsing: predict for a given  $c$  the best transition  $t$ .
- Using properties (**features**) of the parser state.

# Example (parsing features)

Consider following two parsing features:

- $f_1$ : 1 if  $\sigma = [\dots | \text{ART} | \text{NN}]$ , 0 otherwise
- $f_2$ : 1 if  $\sigma = [\dots | \text{APPR} | \text{NE}]$ , 0 otherwise

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For a parser state with  $\sigma = [\dots, \text{APPR}, \text{NE}]$ :

- $f_1(c_i) = 0$
- $f_2(c_i) = 1$
- $\mathbf{x}_i = [0, 1]$

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For a parser state with  $\sigma = [\dots, \text{ART}, \text{NN}]$ :

- $f_1(c_i) = 1$
- $f_2(c_i) = 0$
- $\mathbf{x}_i = [1, 0]$

# Feature-based rules

- Given the features:
  - $f_1$ : 1 if  $\sigma = [\dots | \text{ART} | \text{NN}]$ , 0 otherwise
  - $f_2$ : 1 if  $\sigma = [\dots | \text{APPR} | \text{NE}]$ , 0 otherwise
- $\text{LEFT-ARC}_{\text{DET}}$  when  $f_1 = 1$



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- LEFT-ARC<sub>DET</sub> when  $f_1 = 1$
- RIGHT-ARC<sub>PN</sub> when  $f_2 = 1$

# Data-driven learning

For each sentence  $S_i$  and the corresponding gold standard dependency structure  $g_i$ :

- 1 Parse  $S_i$  using an oracle to reproduce  $G_i$ .
- 2 Extract the transition sequence  $C_{0,m}$  and the corresponding transitions  $T_{0,m}$ .
- 3 For each pair  $(c_i, t_i) \in (C_{0,m}, T_{0,m})$ :
  - 1 Convert  $c_i$  to a feature vector  $\mathbf{x}_i \in \mathbb{R}^d$ .
  - 2 Convert  $t_i$  to a natural number  $y_i \in \mathbb{N}$ .
  - 3  $(\mathbf{x}_i, y_i)$  is a training instance.

# Example

Transition	$\sigma$	$\beta$	$A$
	[ROOT]	[Staatsanwalt, . . .]	$\emptyset$
SH	[ROOT, Staatsanwalt]	[muß, . . .]	$\emptyset$
SH	[ROOT, Staatsanwalt, muß]	[AWO-Konten, . . .]	$\emptyset$
LA <sub>SUBJ</sub>	[ROOT, muß]	[AWO-Konten, . . .]	$A_1 = \{(\text{muß}, \text{SUBJ}, \text{Staatsanwalt})\}$
SH	[ROOT, AWO-Konten]	[prüfen]	$A_1$
SH	[ROOT, AWO-Konten, prüfen]	$\square$	$A_1$
LA <sub>OBJA</sub>	[ROOT, muß, prüfen]	$\square$	$A_2 = A_1 \cup \{(\text{prüfen}, \text{OBJA}, \text{AWO-Konten})\}$
RA <sub>AUX</sub>	[ROOT, muß]	$\square$	$A_3 = A_2 \cup \{(\text{muß}, \text{AUX}, \text{prüfen})\}$
RA <sub>ROOT</sub>	[ROOT]	$\square$	$A_4 = A_3 \cup \{(\text{ROOT}, \text{ROOT}, \text{muß})\}$

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SH	[ROOT, AWO-Konten]	[prüfen]	$A_1$
SH	[ROOT, AWO-Konten, prüfen]	$\emptyset$	$A_1$
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RA <sub>ROOT</sub>	[ROOT]	$\emptyset$	$A_4 = A_3 \cup \{(\text{ROOT}, \text{ROOT}, \text{muß})\}$

- The tuple  $\langle \sigma, \beta, A \rangle$  on each line is a parser state.
- The transition on the next line is the corresponding class.

# Features

- Features are extracted from a parser state  $c_i$  using feature templates.
- Features can use any portion of the parser state:
  - Any token on the stack/buffer.
  - Attributes of a token, such as its part-of-speech tag or lemma.

# Example feature set (Kübler, McDonald, and Nivre 2009)

Address	Form	Lemma	POS-tag	Features	Deprel
$\sigma_0$	+	+	+	+	
$\sigma_1$			+		
LDEP[ $\sigma_0$ ]					+
RDEP[ $\sigma_0$ ]					+
$\beta_0$	+	+	+	+	
$\beta_1$	+		+		
$\beta_2$			+		
$\beta_3$			+		
LDEP[ $\beta_0$ ]					+
RDEP[ $\beta_0$ ]					+

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- We can represent four features in a vector of four components:

a.  $\sigma = [\dots | \text{die} | \text{AWO}]$

b.  $\sigma = [\dots | \text{in} | \text{Japan}]$

c.  $\sigma = [\dots | \text{das} | \text{Auto}]$

d.  $\sigma = [\dots | \text{in} | \text{Sofia}]$

e.  $\sigma = [\dots | \text{Sofia}], \beta = [\text{gewesen} | \dots]$

$$\begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix}$$



# Feature vectors

- The parser state

- $\sigma = [\dots, \text{in}, \text{Sofia}]$
- $\beta = [\text{gewesen}, \dots]$

- Would correspond to the following feature vector:

a.  $\sigma = [\dots | \text{die} | \text{AWO}]$

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c.  $\sigma = [\dots | \text{das} | \text{Auto}]$

d.  $\sigma = [\dots | \text{in} | \text{Sofia}]$

e.  $\sigma = [\dots | \text{Sofia}], \beta = [\text{gewesen} | \dots]$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

# Softmax regression

# Basic linear model

- We introduce a matrix  $\mathbf{W} \in \mathbb{R}^{|T| \times |F|}$ , where:
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  - $|F|$ : the number of features.
- Each row of  $\mathbf{W}$  is a transition-specific weighting of feature vectors.
- If  $\mathbf{x}$  is the feature vector of a parser state, then a simple guide would be:

$$g(\mathbf{x}) = \arg \max_{t \in T} (\mathbf{W}\mathbf{x})_t$$

# The softmax function

The **softmax** function squashes the components of a vector  $\mathbf{u}$ , such that the components sum up to 1:

$$\text{softmax}(\mathbf{u})_i = \frac{e^{\mathbf{u}_i}}{\sum_k e^{\mathbf{u}_k}}$$

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- Softmax can represent a categorical probability distribution  $p(y|\mathbf{x})$ :
  - All output values are in the range  $(0, 1)$ .
  - $\sum_k \text{softmax}(\mathbf{u})_k = 1$
  - $\text{softmax}(\mathbf{u})_y$  is the probability of class  $y$ .

# Softmax for classification

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Known as:

- **logistic regression** in statistics;
- **softmax layer** in neural networks;
- **conditional maximum entropy model** in CL.

# Computing the softmax regression

Given  $\mathbf{x} \in \mathbb{R}^4$  and  $\mathbf{y} \in \mathbb{R}^3$ :

$$\begin{aligned} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} &= \text{softmax} \left( \begin{bmatrix} W_{1,1} & W_{1,2} & W_{1,3} & W_{1,4} \\ W_{2,1} & W_{2,2} & W_{2,3} & W_{2,4} \\ W_{3,1} & W_{3,2} & W_{3,3} & W_{3,4} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) \\ &= \text{softmax} \left( \begin{bmatrix} W_{1,1} \cdot x_1 + W_{1,2} \cdot x_2 + W_{1,3} \cdot x_3 + W_{1,4} \cdot x_4 \\ W_{2,1} \cdot x_1 + W_{2,2} \cdot x_2 + W_{2,3} \cdot x_3 + W_{2,4} \cdot x_4 \\ W_{3,1} \cdot x_1 + W_{3,2} \cdot x_2 + W_{3,3} \cdot x_3 + W_{3,4} \cdot x_4 \end{bmatrix} \right) \end{aligned}$$

# Example

$$\mathbf{W} = \begin{bmatrix} 0.3 & -0.1 & 0.4 & -0.2 \\ -0.2 & 0.6 & 0.5 & -0.9 \\ 0.3 & -0.1 & 0.1 & 0.4 \end{bmatrix}, \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

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$$\mathbf{W}\mathbf{x}^\top = [0.1 \quad -1.1 \quad 0.7]$$

$$\text{softmax}(\mathbf{W}\mathbf{x})^\top = [0.32 \quad 0.10 \quad 0.58]$$